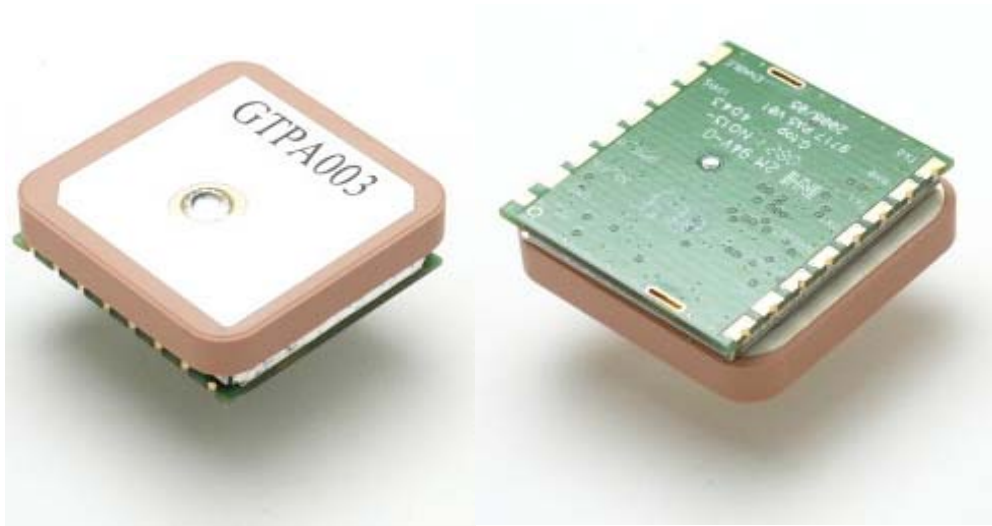




FGPMMOPA5 Datasheet

Rev.A06



51-channel GPS Engine Board SmartAntenna

with MTK Chipset

FGPMMOPA5

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FGPMMOPA5 Datasheet

Rev.A06

History		
Date	Rev.	Description
2008/06/17	A00	First Release
2008/12/15	A01	Modify Operating Temperature Range
2009/1/13	A02	Modify pin description SMT Reflow Soldering Temperature Profile:
2009/3/24	A03	Modify DC characteristics SMT Reflow Soldering Temperature Profile:
2009/5/08	A04	Pin 10 Description Update SMT Reflow Soldering Temperature Profile:
2010/03/23	A05	Add Packing and Handling Section
2010/04/30	A06	Page19: Modify for RMC Magnetic Variation data

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FGPMMOPA5 Datasheet

Rev.A06

Description

The FGPMMOPA5 is a SMT POT (Patch On Top) second generation GPS module. It is more compact in size when compared to first generation. This POT GPS receiver provides a solution that is high in position and speed accuracy performances as well as high sensitivity and tracking capabilities in urban conditions. The GPS chipsets inside the module are designed by **MediaTek Inc.**, the world's leading digital media solution provider and largest fab-less IC company in Taiwan. The module can support up to **51 channels**. This GPS solution enables small form factor devices. It delivers major advancements in GPS performances, accuracy, integration, computing power and flexibility. FGPMMOPA5 designed to simplify the embedded system integration process.

Features

- MediaTek GPS technology
- Dimension: 25.8mm x 25mm x 6.8mm
- Patch Antenna Size: 25mm x 25mm x 4mm
- L1 frequency, C/A code, 51-channel
- Embedded LNA and SAW filter
- With Active patch antenna
- High sensitivity: Up to -158 dBm tracking, superior urban performance¹
- Position Accuracy: Without aid: 3m 2D-RMS
DGPS (RTCM,SBAS(WAAS,EGNOS,MASA)):2.5m 2D-RMS
- Cold Start is under 36 seconds (Typical)¹
- Warm Start is under 33 seconds (Typical)¹
- Hot Start is under 1 second (Typical)¹
- Low power consumption: 58mA@ acquisition, 39mA@ tracking
- Low Shut-Down power consumption: 15uA, typical
- DGPS (WAAS, EGNOS, MSAS) support (optional by firmware)
- Maximum update rate: up to 5Hz
- RoHS compliant

¹ Reference to GPS chipset specification

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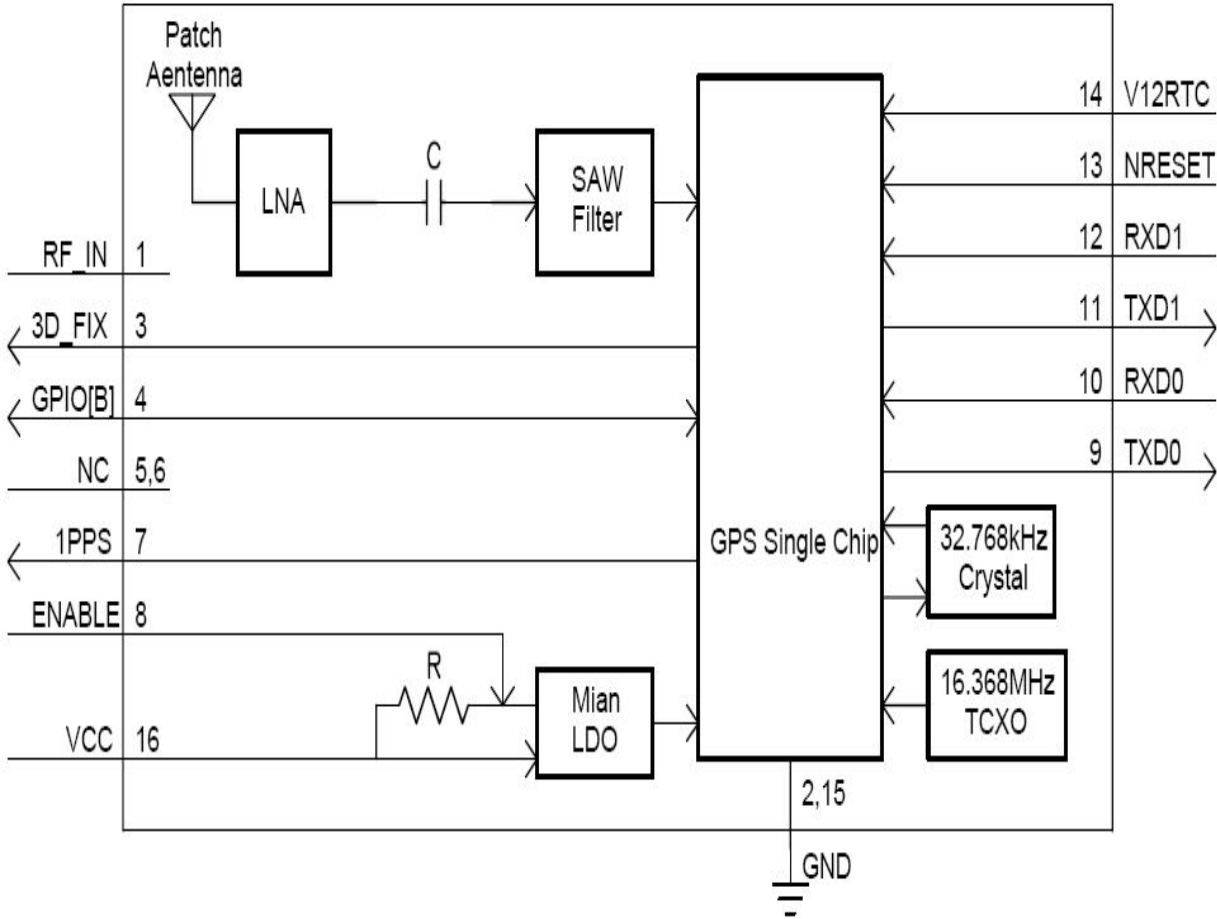
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FGPMMOPA5 Datasheet

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Module Functional Block



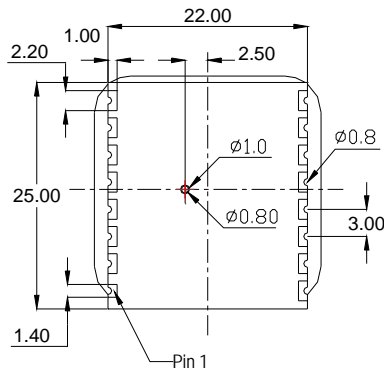
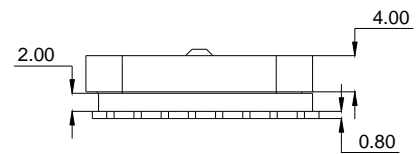
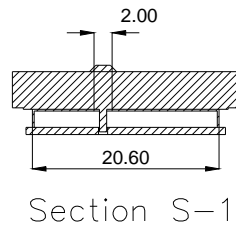
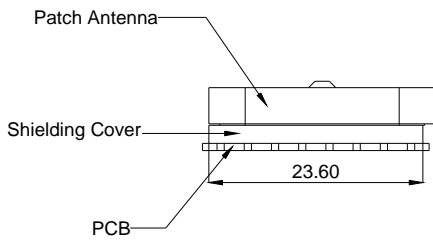
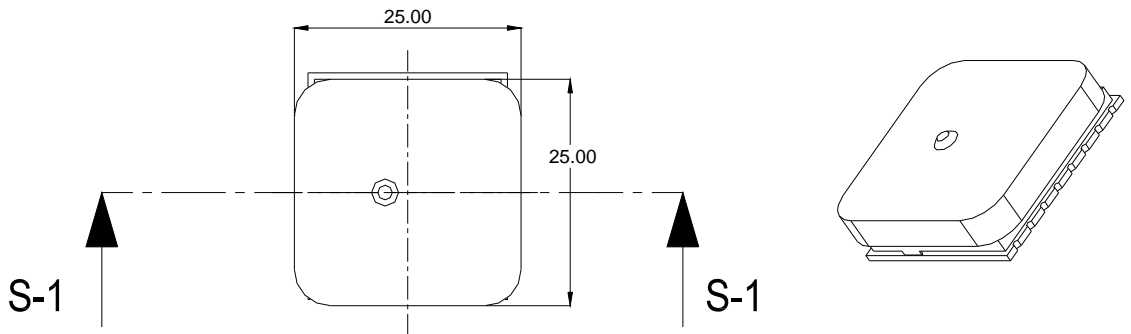
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Mechanical

Dimension: (Unit: mm)



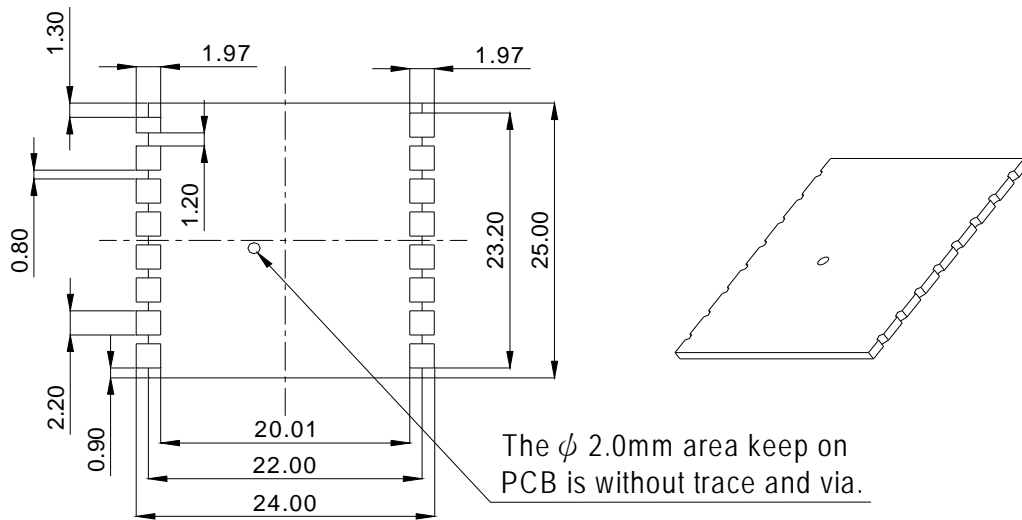
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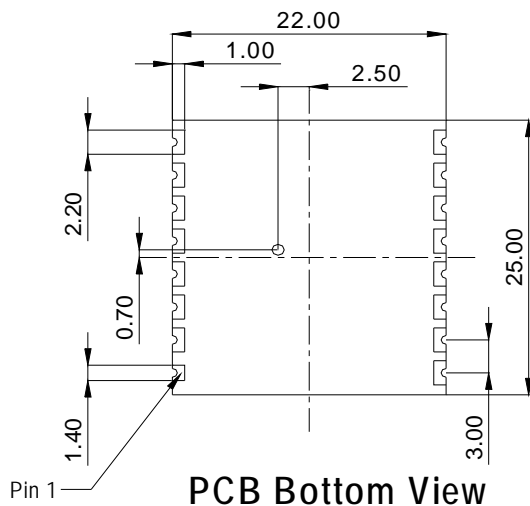
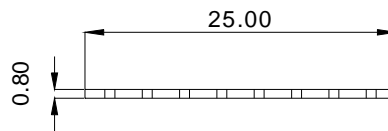
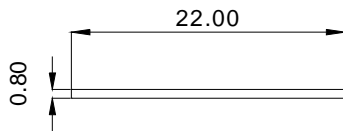
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Recommend PCB Layout Pad:

Dimension: (Unit: mm)



Footprint Top View



PCB Bottom View

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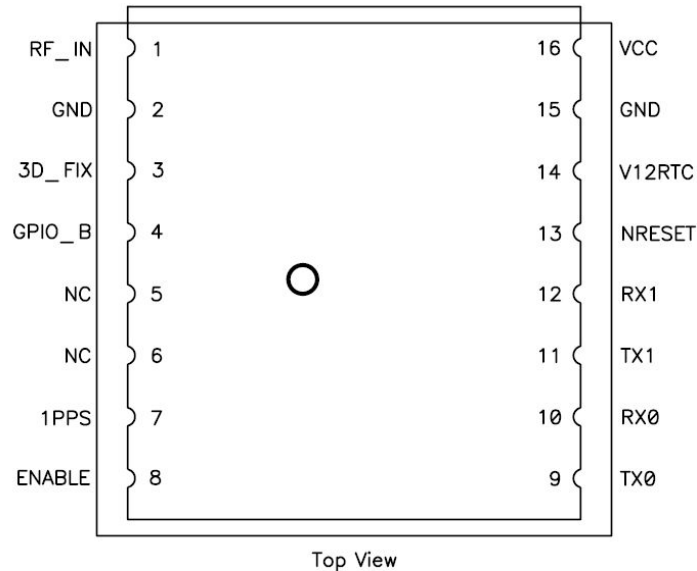
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FGPMMOPA5 Datasheet

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Pin Configuration



Pin Definition

Pin	Name	I/O	Description
1	RF_IN	I	Not connected
2	GND	P	Ground
3	3D_FIX	O	3D-fix indicator
4	GPIO_B	O	General Purpose I/O B, Normally high
5	NC	--	Not connected
6	NC	--	Not connected
7	1PPS	O	1PPS Time Mark Output 2.8V CMOS Level
8	ENABLE	I	Keep open or pull high to Power ON
9	TX0	O	Serial Data Output A for NMEA output
10	RX0	I	Serial Data Input A for Firmware update
11	TX1	O	Serial Data Output B, Not used
12	RX1	I	Serial Data Input B, Not used
13	NRESET	I	Reset Input, Active Low

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FGPMMOPA5 Datasheet

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14	V12RTC	PI	Backup Power for RTC DC 1.2V (Typical) to maintain system operation, 1.0~1.6V DC Power Input, This pin must be connected with power for operation
15	GND	P	Ground
16	VCC	PI	3.0 ~ 5.0V DC Power Input (Typical:3.3V)

Description of I/O Pin

RF_IN (Pin 1)

This pin is NC pin. It is not connected.

NC (Pin5 and Pin6)

This pin is NC pin. It is not connected.

GND (Pin2, Pin15)

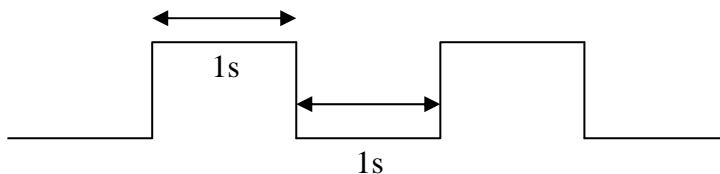
The ground of the module

3D_FIX (Pin3)

The GPIO_A was assigned as fix flag output. If not used, keep floating.

■ Before 2D Fix

The GPIO_A should continuously output one-second high-level with one-second low-level signal.



■ After 2D or 3D Fix

The GPIO_A should continuously output low-level signal.

Low

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GPIO_B (Pin4)

Reserved for customized purpose. If not used, keep floating.

1PPS (Pin7)

This pin provides one pulse-per-second output from the module, which is synchronized to GPS time. If not used, keep floating.

ENABLE (Pin8)

Keep open or pull high to Power ON. Pull low to shutdown the module.

TX0 (Pin9)

This is the UART transmitter of the module. It outputs the GPS information for application.

RX0 (Pin10)

This is the UART receiver of the module. It is used to receive software commands and firmware update.

TX1 (Pin11)

Not used, keep floating.

RX1 (Pin12)

Not used, keep floating.

NRESET (Pin13)

With a low level, it causes the module to reset. If not used, keep floating.

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FGPMMOPA5 Datasheet

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V12RTC (Pin14)

The voltage should be kept between 1.0V~1.6V (**Typical: 1.2V**) for baseband clock to maintain system operation. **The system will not be active if this pin is not connected to a power source. This pin must be connected with power or to another rechargeable coin battery.**

The V12RTC is backup power for GPS chipset to keep RTC running and enables it to get quick 3D position fix during the next power on.

The pin must be connected for normal operation.

VCC (Pin16)

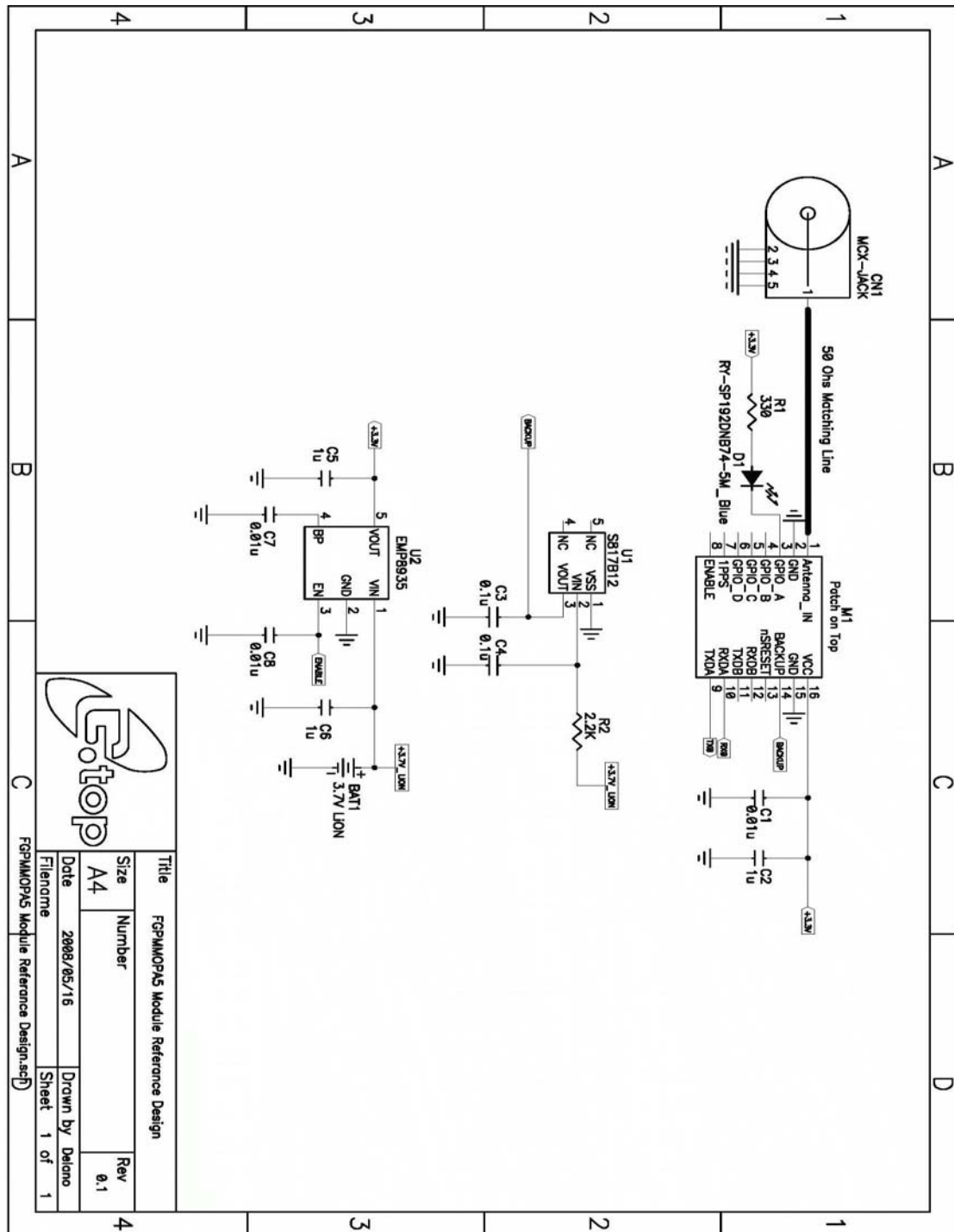
The main DC power supply for the GPS module. The voltage should be kept between from 3.0V to 5.0V. (**Typical: 3.3V**)

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Reference Design



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FGPMMOPA5 Datasheet

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Specification

General	
Chipset	MTK MT3318
Frequency	L1, 1575.42MHz
C/A Code	1.023 MHz
Channels	51 channels
DGPS	SBAS (WAAS, EGNOS, MSAS) (Default: disable)
Datum	WGS84(Default), Tokyo-M, Tokyo-A, User Define
CPU	ARM7TDMI
Dimensions	
Length/Width/Height	25.8*25*6.8mm
Weight	12g
Performance Characteristics	
Position Accuracy	Without aid: 3m 2D-RMS
	DGPS(RTM,SBAS(WAAS,EGNOS,MASA)):2.5m 2D-RMS
Velocity Accuracy	Without aid:0.1 m/s
	DGPS (RTCM, SBAS (WAAS, EGNOS, MSAS)):0.05m/s
Acceleration	Without aid:< 4g
	DGPS (RTCM, SBAS (WAAS, EGNOS, MSAS)):< 4g
Timing Accuracy	100 ns RMS
Sensitivity ¹	Acquisition:-146dBm (Cold Start)
	Reacquisition: -156dBm
	Tracking: -158dBm
Maximum Update Rate	Up to 5Hz (Default: 1Hz)

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FGPMMOPA5 Datasheet

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Acquisition (Open sky, stationary)	
Reacquisition Time ¹	Less than 1 second
Hot start ¹	1s (Typical)
Warm start ¹	33s (Typical)
Cold start ¹	36s (Typical)
Dynamic	
Altitude	Maximum 18,000m
Velocity	Maximum 515m/s
Acceleration	Maximum 4g
I/O	
Signal Output	8 data bits, no parity, 1 stop bit
Available Baud Rates	4800/9600/38400/57600/115200 bps
Protocols	NMEA 0183 v3.01 (Default:GGA,GSA,GSV,RMC,VTG) RTCM MTK NMEA Command Network Assistance Messages
Data output Interface	
Protocol messages	9600 bps/8/N/1 (Default) 1Hz(Default)
Output format	GGA(1sec),GSA(1sec),RMC(1sec),VTG(1sec), GSV(5sec) (Default)
Environment	
Operating Temperature	-40 °C to 85 °C
Storage Temperature	-50 °C to 90 °C
Operating Humidity	5% to 95% (no condensing)

¹ Reference to GPS chipset specification

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DC Characteristics

Parameter	Condition	Min.	Typ.	Max.	Unit
Operation supply Voltage	—	3.0	3.3	5.0	V
Operation supply Ripple Voltage	—	—	—	50	mVpp
Backup Battery Voltage	—	1.0	1.2	1.6	V
RXD0 TTL H Level	P3V3=3.3V	2.1	—	2.8	V
RXD0 TTL L Level	P3V3=3.3V	0	—	0.9	V
TXD0 TTL H Level	P3V3=3.3V	2.1	—	2.8	V
TXD0 TTL L Level	P3V3=3.3V	0	—	0.8	V
Power Consumption @ 3.3V	Acquisition	53	58	63	mA
	Tracking	34	39	44	mA
Backup Power Consumption @ 1.2V	25°C	—	10	—	uA
Shut-down Power Consumption (via enable pin)	25°C	—	15	—	uA

NMEA Output Sentence

Table-1 lists each of the NMEA output sentences specifically developed and defined by MTK for use within MTK products

NMEA Output Sentence		Table-1
Option	Description	
GGA	Time, position and fix type data.	
GSA	GPS receiver operating mode, active satellites used in the position solution, and DOP values.	
GSV	The number of GPS satellites in view satellite ID numbers, elevation, azimuth, and SNR values.	
RMC	Time, date, position, course and speed data. Recommended Minimum Navigation Information.	
VTG	Course and speed information relative to the ground.	

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FGPMMOPA5 Datasheet

Rev.A06

GGA—Global Positioning System Fixed Data. Time, Position and fix related data for a GPS receiver

Table-2 contains the values for the following example:

\$GPGGA,011528.000,2307.1203,N,12016.4430,E,1,7,1.11,18.3,M,17.8,M,,*6F

GGA Data Format			Table-2
Name	Example	Units	Description
Message ID	\$GPGGA		GGA protocol header
UTC Time	011528.000		hhmmss.sss
Latitude	2307.1203		ddmm.mmmm
N/S Indicator	N		N=north or S=south
Longitude	12016.4430		dddmm.mmmm
E/W Indicator	E		E=east or W=west
Position Fix Indicator	1		See Table-3
Satellites Used	7		Range 0 to 14
HDOP	1.11		Horizontal Dilution of Precision
MSL Altitude	18.3	meters	Antenna Altitude above/below mean-sae-level
Units	M	meters	Units of antenna altitude
Geoidal Separation	17.8	meters	
Units	M	meters	Units of geoidal separation
Age of Diff. Corr.		second	Null fields when DGPS is not used
Checksum	*6F		
<CR> <LF>			End of message termination

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FGPMMOPA5 Datasheet

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Position Fix Indicator		Table-3
Value	Description	
0	Fix not available	
1	GPS fix	
2	Differential GPS fix	

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FGPMMOPA5 Datasheet

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GSA—GNSS DOP and Active Satellites

Table-4 contains the values for the following example:

\$GPGSA,A,3,23,05,13,04,17,12,10,,,,,1.44,1.11,0.92*0F

GSA Data Format				Table-4
Name	Example	Units	Description	
Message ID	\$GPGSA		GSA protocol header	
Mode 1	A		See Table-5	
Mode 2	3		See Table-6	
Satellite Used	23		SV on Channel 1	
Satellite Used	05		SV on Channel 2	
....	
Satellite Used			SV on Channel 12	
PDOP	1.44		Position Dilution of Precision	
HDOP	1.11		Horizontal Dilution of Precision	
VDOP	0.92		Vertical Dilution of Precision	
Checksum	*0F			
<CR> <LF>			End of message termination	

Mode 1		Table-5
Value	Description	
M	Manual—forced to operate in 2D or 3D mode	
A	2D Automatic—allowed to automatically switch 2D/3D	
Mode 2		Table-6
Value	Description	
1	Fix not available	
2	2D (< 4 SVs used)	
3	3D (\geq 4 SVs used)	

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FGPMMOPA5 Datasheet

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GSV—GNSS Satellites in View

Table-7 contains the values for the following example:

\$GPGSV,2,1,08,17,52,126,47,04,49,015,49,10,40,238,46,13,34,071,46*7A

\$GPGSV,2,2,08,12,20,299,43,23,13,046,45,05,12,304,44,02,,,48*4A

GSV Data Format			Table-7
Name	Example	Units	Description
Message ID	\$GPGSV		GSV protocol header
Number of Messages	2		Range 1 to 3 <i>(Depending on the number of satellites tracked, multiple messages of GSV data may be required.)</i>
Message Number1	1		Range 1 to 3
Satellites in View	08		
Satellite ID	17		Channel 1 (Range 1 to 32)
Elevation	52	degrees	Channel 1 (Maximum 90)
Azimuth	126	degrees	Channel 1 (True, Range 0 to 359)
SNR (C/No)	47	dBHz	Range 0 to 99, (null when not tracking)
....
Satellite ID	13		Channel 4 (Range 1 to 32)
Elevation	34	degrees	Channel 4 (Maximum 90)
Azimuth	071	degrees	Channel 4 (True, Range 0 to 359)
SNR (C/No)	46	dBHz	Range 0 to 99, (null when not tracking)
Checksum	*7A		
<CR> <LF>			End of message termination

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FGPMMOPA5 Datasheet

Rev.A06

RMC—Recommended Minimum Navigation Information

Table-8 contains the values for the following example:

\$GPRMC,011528.000,A,2307.1203,N,12016.4430,E,0.21,198.97,170407,3.05,W,A*5A

RMC Data Format			Table-8
Name	Example	Units	Description
Message ID	\$GPRMC		RMC protocol header
UTC Time	011528.000		hhmmss.sss
Status	A		A=data valid or V=data not valid
Latitude	2307.1203		ddmm.mmmm
N/S Indicator	N		N=north or S=south
Longitude	12016.4430		dddmm.mmmm
E/W Indicator	E		E=east or W=west
Speed Over Ground	0.21	knots	
Course Over Ground	198.97	degrees	True
Date	170407		ddmmyy
Magnetic Variation	3.05, W	degrees	E=east or W=west (Need GlobalTop customization service)
Mode	A		A= Autonomous mode D= Differential mode E= Estimated mode
Checksum	*5A		
<CR> <LF>			End of message termination

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VTG—Course and speed information relative to the ground.

Table-9 contains the values for the following example:

\$GPVTG,198.97,T,,M,0.21,N,0.39,K,A*3D

VTG Data Format			Table-9
Name	Example	Units	Description
Message ID	\$GPVTG		VTG protocol header
Course	198.97	degrees	Measured heading
Reference	T		True
Course		degrees	Measured heading
Reference	M		Magnetic <i>(Need Global Top customization service.)</i>
Speed	0.21	knots	Measured horizontal speed
Units	N		Knots
Speed	0.39	km/hr	Measured horizontal speed
Units	K		Kilometers per hour
Mode	A		A= Autonomous mode D= Differential mode E= Estimated mode
Checksum	*3D		
<CR> <LF>			End of message termination

MTK NMEA Command Protocol

Packet Type:

103 PMTK_CMD_COLD_START

Packet Meaning:

Cold Start: Don't use Time, Position, Almanacs and Ephemeris data at re-start.

Example:

\$PMTK103*30<CR><LF>

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Packing and Handling

GPS modules, like any other SMD devices, are sensitive to moisture, electrostatic discharge, and temperature. By following the standards outlined in this document for GlobalTop GPS module storage and handling, it is possible to reduce the chances of them being damaged during production set-up. This document will go through the basics on how GlobalTop packages its modules to ensure they arrive at their destination without any damages and deterioration to performance quality, as well as some cautionary notes before going through the surface mount process.

- ⚠ Please read the sections II to V carefully to avoid damages permanent damages due to moisture intake**
- ⚠ GPS receiver modules contain highly sensitive electronic circuits and are electronic sensitive devices and improper handling without ESD protections may lead to permanent damages to the modules. Please read section VI for more details.**

Moisture Sensitivity

GlobalTop GPS modules are moisture sensitive, and must be pre-baked before going through the solder reflow process. It is important to know that:

GlobalTop GPS modules must complete solder reflow process in 72 hours after pre-baking.

This maximum time is otherwise known as "Floor Life"

If the waiting time has exceeded 72 hours, it is possible for the module to suffer damages during the solder reflow process such as cracks and delamination of the SMD pads due to excess moisture pressure.

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Packing

GlobalTop GPS modules are packed in such a way to ensure the product arrives to SMD factory floor without any damages.

GPS modules are placed individually on to the packaging tray. The trays will then be stacked and packaged together.

Included are:

1. Two packs of desiccant for moisture absorption
2. One moisture level color coded card for relative humidity percentage.

Each package is then placed inside an antistatic bag (or PE bag) that prevents the modules from being damaged by electrostatic discharge.



Figure 1: One pack of GPS modules

Each bag is then carefully placed inside two levels of cardboard carton boxes for maximum protection.



Figure 2: Box protection

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The moisture color coded card provides an insight to the relative humidity percentage (RH). When the GPS modules are taken out, it should be around or lower than 30% RH level.

Outside each electrostatic bag is a caution label for moisture sensitive device.

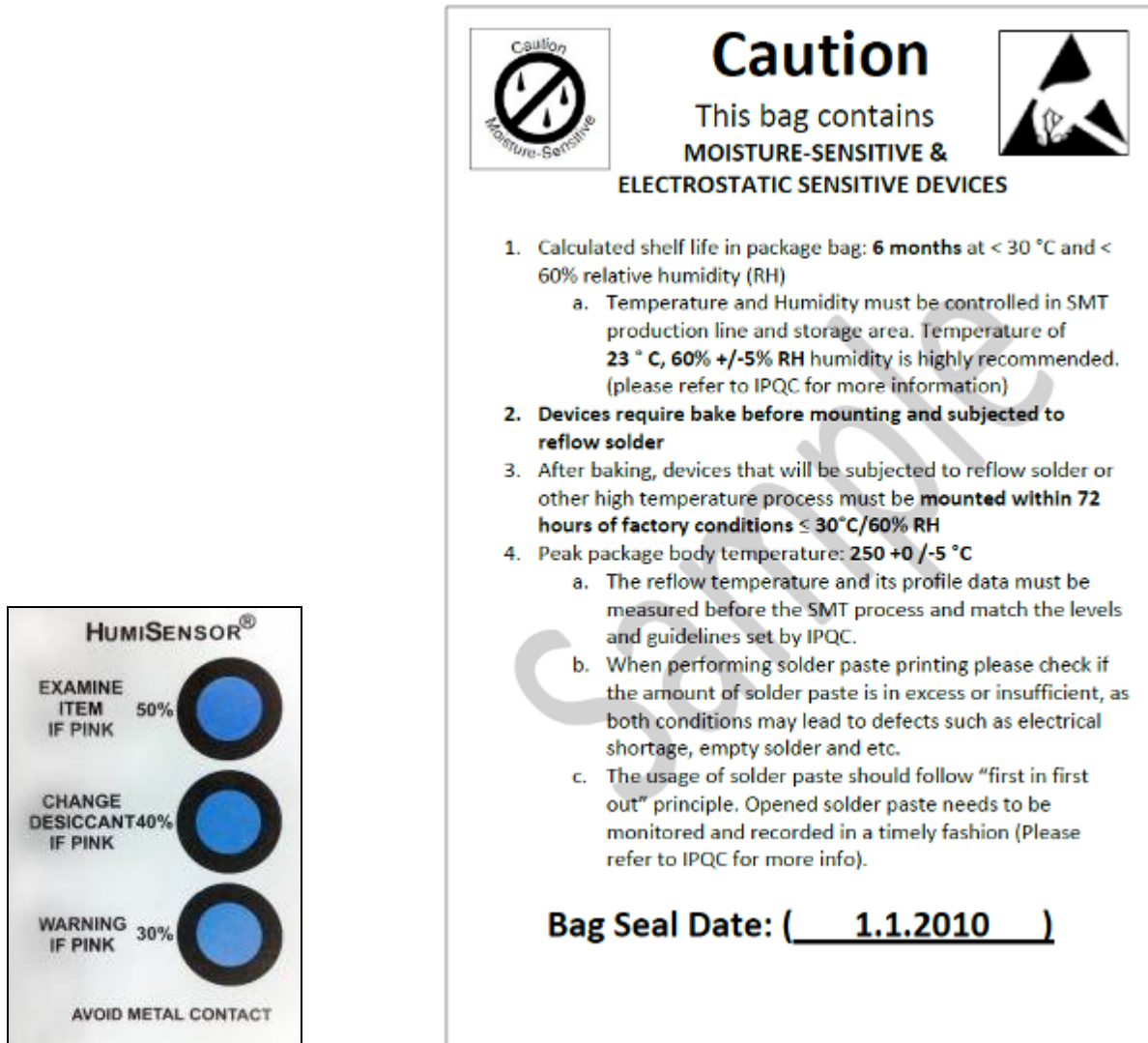


Figure 3: Example of moisture color coded card and caution label

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Storage and Floor Life Guideline

Since GlobalTop modules must undergo solder-reflow process in 72 hours after it has gone through pre-baking procedure, therefore if it is not used by then, it is recommended to store the GPS modules in dry places such as dry cabinet.

The approximate shelf life for GlobalTop GPS modules packages is 6 months from the bag seal date, when store in a non-condensing storage environment (<30°C/60% RH)

⚠ It is important to note that it is a required process for GlobalTop GPS modules to undergo pre-baking procedures, regardless of the storage condition.

Drying

Because the vapor pressures of moisture inside the GPS modules increase greatly when it is exposed to high temperature of solder reflow, in order to prevent internal delaminating, cracking of the devices, or the “popcorn” phenomenon, it is a **necessary requirement** for GlobalTop GPS module to undergo pre-baking procedure before any high temperature or solder reflow process.

The recommendation baking time for GlobalTop GPS module is as follows:

✓ **60°C for 8 to 12 hours**

Once baked, the module’s floor life will be “reset”, and has additional 72 hours in normal factory condition to undergo solder reflow process.

⚠ Please limit the number of times the GPS modules undergoes baking processes as repeated baking process has an effect of reducing the wetting effectiveness of the SMD pad contacts. This applies to all SMT devices.

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⚠ Oxidation Risk: Baking SMD packages may cause oxidation and/or intermetallic growth of the terminations, which if excessive can result in solderability problems during board assembly. The temperature and time for baking SMD packages are therefore limited by solderability considerations. The cumulative bake time at a temperature greater than 90°C and up to 125°C shall not exceed 96 hours. Bake temperatures higher than 125°C are now allowed.

ESD Handling



Please carefully follow the following precautions to prevent severe damage to GPS modules.

GlobalTop GPS modules are sensitive to electrostatic discharges, and thus are Electrostatic Sensitive Devices (ESD). Careful handling of the GPS modules and in particular to its patch antenna (if included) and RF_IN pin, must follow the standard ESD safety practices:

- ✓ Unless there is a galvanic coupling between the local GND and the PCB GND, then the first point of contact when handling the PCB shall always be between the local GND and PCB GND.
- ✓ Before working with RF_IN pin, please make sure the GND is connected
- ✓ When working with RF_IN pin, do not contact any charges capacitors or materials that can easily develop or store charges such as patch antenna, coax cable, soldering iron.
- ✓ Please do not touch the mounted patch antenna to prevent electrostatic discharge from the RF input
- ✓ When soldering RF_IN pin, please make sure to use an ESD safe soldering iron (tip).

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*All the information in this sheet can be used only for Pb-free certification.

SMT Reflow Soldering Temperature Profile:

(Reference Only)

Average ramp-up rate (25 ~ 150°C): 3°C/sec. max.

Average ramp-up rate (270°C to peak): 3°C/sec. max.

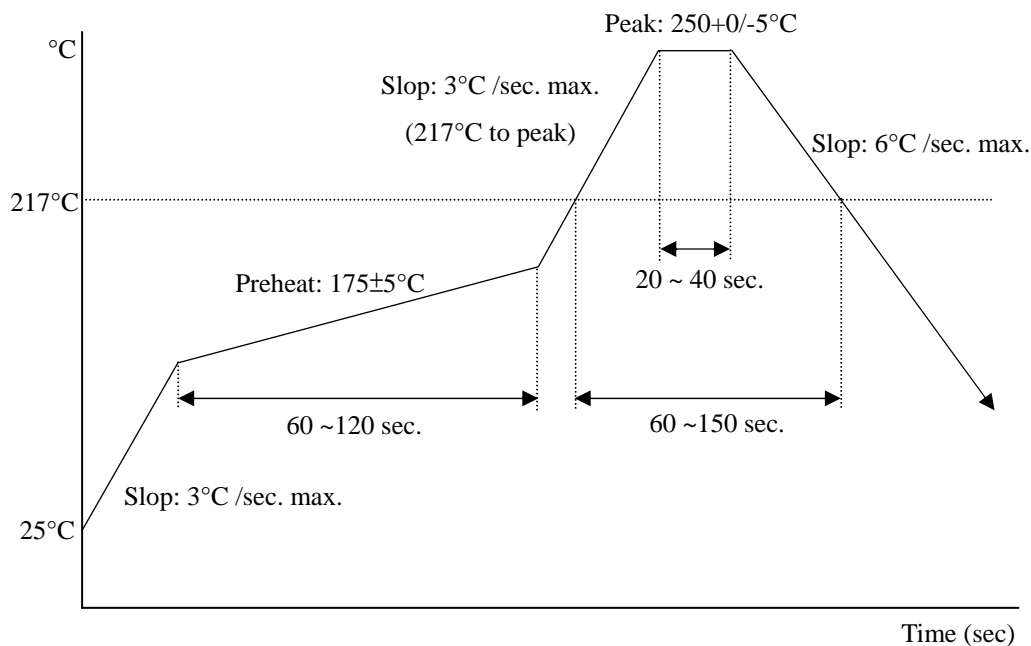
Preheat: 175 ± 25°C, 60 ~ 120 seconds

Temperature maintained above 217°C: 60~150 seconds

Peak temperature: 250 +0/-5°C, 20~40 seconds

Ramp-down rate: 6°C /sec. max.

Time 25°C to peak temperature: 8 minutes max.



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Notes:

1. Module must be pre-baked **before** going through SMT solder reflow process.
2. The usage of solder paste should follow “first in first out” principle. Opened solder paste needs to be monitored and recorded in a timely fashion (can refer to IPQC for related documentation and examples).
3. Temperature and humidity must be controlled in SMT production line and storage area. Temperature of 23°C, 60±5% RH humidity is recommended. (please refer to IPQC for related documentation and examples)
4. When performing solder paste printing, please notice if the amount of solder paste is in excess or insufficient, as both conditions may lead to defects such as electrical shortage, empty solder and etc.
5. The reflow temperature and its profile data must be measured before the SMT process and match the levels and guidelines set by IPQC.

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Manual Soldering:

Soldering iron:

Bit Temperature: Under 380°C

Time: Under 3 sec.

Notes:

1. Please do not directly touch the soldering pads on the surface of the PCB board, in order to prevent further oxidation
2. The solder paste must be defrosted to room temperature before use so it can return to its optimal working temperature. The time required for this procedure is unique and dependent on the properties of the solder paste used.
3. The steel plate must be properly assessed before and after use, so its measurement stays strictly within the specification set by SOP.
4. Please watch out for the spacing between soldering joint, as excess solder may cause electrical shortage
5. Please exercise with caution and do not use extensive amount of flux due to possible siphon effects on neighboring components, which may lead to electrical shortage.
6. Please do not use the heat gun for long periods of time when removing the shielding or inner components of the GPS module, as it is very likely to cause a shift to the inner components and will leads to electrical shortage.

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